

THE DISTRIBUTION OF STRESS IN A RUBBER-LIKE ELASTIC MATERIAL
BOUNDED INTERNALLY BY A RIGID SPHERICAL INCLUSION SUBJECTED
TO A CENTRAL FORCE

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Introduction

In this paper exact closed form solutions are obtained for the second-order effects in an infinite incompressible elastic medium containing a bonded rigid spherical inclusion which is subjected to a central force. The second-order elasticity theory adequately describes the mechanical behaviour of most rubber-like materials at moderately large strains. A displacement function technique is employed in the solution of the second-order problem

Analysis

The differential equations which arise in formulating the mathematical theory of highly elastic rubber-like materials are generally non-linear in character. Approximate methods of analysis are therefore of particular value in instances where exact solutions of these non-linear differential equations are not readily obtainable. The method of successive approximations is one such technique which has received considerable interest. Second-order elasticity theory considers the successive approximation procedure to include terms which are quadratic in the displacement gradients, and adequately describes the mechanical behaviour of most rubber-like materials at moderately large strains.

The general theory of second-order elasticity for axially symmetric deformations of isotropic incompressible elastic

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materials was developed by Selvadurai and Spencer [1]. This particular method of analysis of second-order effects is facilitated by the introduction of a displacement function, Ψ , which reduces the problem to the solution of a single equation of the form $E^4\Psi = f(S,\theta)$, where E^2 is Stokes' differential operator, $f(S,\theta)$ depends only on the first-order or classical elasticity solution and S,θ are the spherical polar coordinates of the reference configuration.

In this paper we consider the problem of an incompressible infinite elastic medium containing a bonded rigid spherical inclusion which is subjected to a central resultant force. This problem is of importance in the analysis of stress concentrations in multiphase rubber-like materials and in bonded rubber mountings. It also serves as a useful mechanical analogue of Kelvin's problem for the concentrated force acting at the interior of an infinite elastic solid. The solutions for the second-order displacement and stress components are presented in exact closed form.

Basic equations

The general theory of second-order elasticity is given in Green and Adkins [2]. A detailed account of the displacement function formulation of the axially symmetric second-order problem is given by Selvadurai and Spencer [1]. For completeness, we shall briefly outline the relevant results.

The spherical polar coordinates of the reference configuration are denoted by (S,ϕ,θ) such that

$$R = S \sin \theta, \quad Z = S \cos \theta, \quad (1)$$

where R,Z are the cylindrical polar coordinates. We restrict our attention to a state of stress which is symmetric about the Z -axis. By using the displacement function technique the solution of the first-order or the classical elasticity problem is reduced to the solution of the equations

$$E^4\Psi_1 = 0, \quad \nabla^2 p_1 = 0, \quad (2)$$

where Ψ_1 is the first-order displacement function and p_1 is the first-order hydrostatic pressure, subject to the particular

boundary conditions of the problem. The operators E^2 and ∇^2 are, respectively, Stokes' and Laplace's differential operators given by

$$E^2 = \frac{\partial^2}{\partial S^2} + \frac{1}{S^2} \frac{\partial^2}{\partial \theta^2} - \frac{\cot \theta}{S^2} \frac{\partial}{\partial \theta}, \quad (3)$$

$$\nabla^2 = \frac{\partial^2}{\partial S^2} + \frac{2}{S} \frac{\partial}{\partial S} + \frac{1}{S^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cot \theta}{S^2} \frac{\partial}{\partial \theta}, \quad (4)$$

and $E^4 = E^2 E^2$.

The first-order displacement components u_1 and w_1 in the S, θ directions are completely determined from the first-order displacement function Ψ_1 by means of the relations

$$u_1 = -\frac{1}{S^2 \sin \theta} \frac{\partial \Psi_1}{\partial \theta}, \quad w_1 = \frac{1}{S \sin \theta} \frac{\partial \Psi_1}{\partial S}. \quad (5)$$

The first-order constitutive equation is

$$\underline{T}_1 = -p_1 \underline{I} + \mu \underline{C}_1, \quad (6)$$

where \underline{T}_1 is the first-order component of the Cauchy stress tensor; μ is the linear elastic shear modulus; p_1 is the first-order hydrostatic pressure; \underline{I} is the unit matrix and

$$\underline{C}_1 = \underline{G}_1 + \underline{G}_1^T, \quad (7)$$

where

$$\underline{G}_1 = \begin{pmatrix} \frac{\partial u_1}{\partial S} & 0 & \frac{1}{S} \frac{\partial u_1}{\partial \theta} - \frac{w_1}{S} \\ 0 & \frac{u_1}{S} + \frac{w_1}{S} \cot \theta & 0 \\ \frac{\partial w_1}{\partial S} & 0 & \frac{u_1}{S} + \frac{1}{S} \frac{\partial w_1}{\partial \theta} \end{pmatrix} \quad (8)$$

The solution of the second-order problem for an isotropic incompressible elastic material reduces to the solution of the equations

$$E^4 \Psi_2 = \frac{\sin \theta}{\mu} \left\{ \frac{\partial}{\partial S} (S H_2) - \frac{\partial H_1}{\partial \theta} \right\}, \quad (9)$$

$$\nabla^2 p_2 = - \left\{ \frac{\partial H_1}{\partial S} + \frac{2H_1}{S} + \frac{1}{S} \frac{\partial H_2}{\partial \theta} + H_2 \frac{\cot \theta}{S} \right\}, \quad (10)$$

where Ψ_2 is the second-order displacement function, p_2 is the second-order hydrostatic pressure and

$$H_1 = - \left\{ \frac{\partial P'_{Ss}}{\partial S} + \frac{1}{S} \frac{\partial P'_{\theta s}}{\partial \theta} + \frac{1}{S} \left[2P'_{Ss} - P'_{\phi\phi} - P'_{\theta\theta} + P'_{\theta s} \cot \theta \right] \right\}, \quad (11)$$

$$H_2 = - \left\{ \frac{\partial P'_{S\theta}}{\partial S} + \frac{1}{S} \frac{\partial P'_{\theta\theta}}{\partial \theta} + \frac{1}{S} \left[\left(P'_{\theta\theta} - P'_{\phi\phi} \right) \cot \theta + 2P'_{S\theta} + P'_{\theta s} \right] \right\}.$$

The terms P'_{Ss}, \dots , etc. are the elements of a non-symmetric matrix \underline{P}'_2 given by

$$\underline{P}'_2 = \begin{pmatrix} P'_{Ss} & 0 & P'_{S\theta} \\ 0 & P'_{\phi\phi} & 0 \\ P'_{\theta s} & 0 & P'_{\theta\theta} \end{pmatrix}, \quad (12)$$

and

$$\underline{P}'_2 = p_1 \underline{G}_1 + \frac{1}{2} \mu \left[D \underline{C}_1 - \underline{G}_1^2 + \left(\underline{G}^T \right)^2 + \frac{w_1}{S} (\underline{Q} \underline{C}_1 - \underline{C}_1 \underline{Q}) \right] - 2C_2 \underline{C}_1^2. \quad (13)$$

In (13) the operator D is given by

$$D = u_1 \frac{\partial}{\partial S} + \frac{w_1}{S} \frac{\partial}{\partial \theta}, \quad (14)$$

\underline{Q} denotes the skew-symmetric matrix

$$\underline{Q} = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad (15)$$

and C_2 is a material constant. The second-order displacement components u_2 and w_2 can be represented in the form

$$u_2 = u'_2 + u''_2, \quad w_2 = w'_2 + w''_2, \quad (16)$$

where

$$u'_2 = - \frac{1}{S^2 \sin \theta} \frac{\partial \Psi_2}{\partial \theta}, \quad w'_2 = \frac{1}{S \sin \theta} \frac{\partial \Psi_2}{\partial S}, \quad (17)$$

and

$$u''_2 = \frac{1}{2} D u_1 - \frac{1}{2} \frac{w_1^2}{S}, \quad w''_2 = \frac{1}{2} D w_1 + \frac{1}{2} \frac{u_1 w_1}{S}. \quad (18)$$

The second-order constitutive equation is

$$\underline{T}_2 = -p_2 \underline{I} + \mu \underline{C}'_2 + \underline{P}'_2 + \frac{w_1}{S} \left\{ \underline{T}_1 \underline{Q} - \underline{Q} \underline{T}_1 \right\} + \underline{G}_1 \underline{T}_1, \quad (19)$$

where \underline{T}_2 is the second-order component of the Cauchy stress tensor and

$$\underline{C}'_2 + \underline{G}'_2 + \underline{G}'_2{}^T, \quad (20)$$

where

$$\underline{G}'_2 = \begin{pmatrix} \partial u'_2 & 0 & \frac{1}{S} \frac{\partial u'_2}{\partial \theta} - \frac{w'_2}{S} \\ 0 & \frac{u'_2}{S} + \frac{w'_2}{S} \cot \theta & 0 \\ \frac{\partial w'_2}{\partial S} & 0 & \frac{u'_2}{S} + \frac{1}{S} \frac{\partial w'_2}{\partial \theta} \end{pmatrix}. \quad (21)$$

To the second-order in terms of the non-dimensional parameter ε

$$u = \varepsilon u_1 + \varepsilon^2 u_2; \quad w = \varepsilon w_1 + \varepsilon^2 w_2; \quad \tilde{T} = \varepsilon \tilde{T}_1 + \varepsilon^2 \tilde{T}_2. \quad (22)$$

Spherical inclusion subjected to a resultant force

Consider an incompressible infinite elastic medium which is bounded internally by a rigid spherical inclusion of radius a . The inclusion is in welded contact with the elastic medium. The inclusion is subjected to a central force (F) which causes a rigid body translation ξ . The cylindrical polar coordinate system of the reference configuration is chosen such that the Z -axis coincides with the line of action of F (Fig.1).

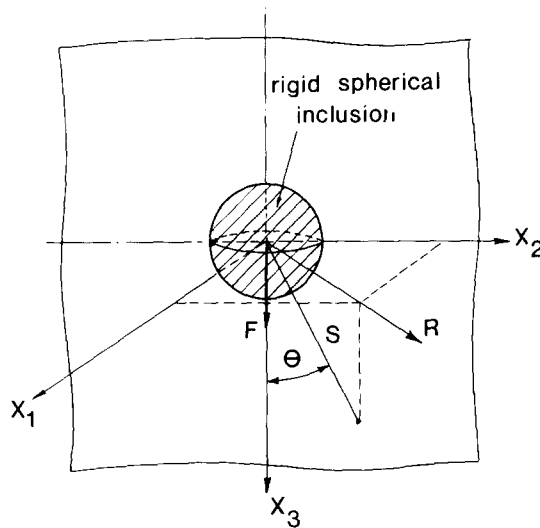


FIG.1

Geometry of the spherical inclusion and the coordinate system

It may be verified that the first-order displacement function

$$\varepsilon \psi_1 = \frac{\xi}{4a} \left\{ \frac{a^4}{S} - 3a^2 S \right\} \sin^2 \theta, \quad (23)$$

satisfies displacement boundary conditions

$$u_1 = \xi \cos \theta, \quad w_1 = -\xi \sin \theta, \quad \text{on } S = a, \quad (24)$$

and gives stress components which tend to zero as $S \rightarrow \infty$. The small real dimensionless parameter is chosen to be equal to $(\xi/4a)$. The first-order displacement and stress components can be written as

$$u_1^* = \left\{ -\frac{2}{S^{*3}} + \frac{6}{S^*} \right\} \cos \theta, \quad w_1^* = \left\{ -\frac{1}{S^{*3}} - \frac{3}{S^*} \right\} \sin \theta, \quad (25)$$

$$\begin{aligned} T_{ss}^{(1)*} &= \left\{ \frac{12}{S^{*4}} - \frac{18}{S^{*2}} \right\} \cos \theta, & T_{\phi\phi}^{(1)*} &= T_{\theta\theta}^{(1)*} = -\frac{6}{S^{*4}} \cos \theta, \\ T_{s\theta}^{(1)*} &= \frac{6}{S^{*4}} \sin \theta, \end{aligned} \quad (26)$$

where (*) denote the dimensionless variables which can be related to the physical variables according to the following:

$$u_1 = au_1^*, \quad w_1 = aw_1^*, \quad T_1 = \mu T_1^*. \quad (27)$$

If the expressions (25) and (26) for the first-order displacement and stress components are substituted in (9), the inhomogeneous differential equation for the second-order displacement function Ψ_2^* ($= \Psi_2/a^3$) reduces to

$$E^{*4} \Psi_2^* = 216 \left\{ \frac{4C_2}{\mu} - 1 \right\} \left\{ \frac{2}{S^{*7}} - \frac{1}{S^{*5}} \right\} \sin^2 \theta \cos \theta, \quad (28)$$

where

$$E^{*2} = \frac{\partial^2}{\partial S^{*2}} + \frac{1}{S^{*2}} \frac{\partial^2}{\partial \theta^2} - \frac{\cot \theta}{S^{*2}} \frac{\partial}{\partial \theta}. \quad (29)$$

A particular integral of (28) is

$$\Psi_{2P}^* = \chi \left\{ \frac{3}{S^{*3}} + \frac{9}{S^{*5}} \right\} \sin^2 \theta \cos \theta, \quad (30)$$

where $\chi = (C_2 - C_1)/(C_2 + C_1)$, and C_1 is an elastic constant such that $2(C_1 + C_2) = \mu$. It can be verified that the second-order displacement components derived from (30) and (16) do not satisfy displacement boundary conditions $u_2^*(1, \theta) = w_2^*(1, \theta) = 0$, on the inclusion-elastic medium interface. These boundary conditions can be explicitly satisfied by employing solutions of the homogeneous equation $E^{*4} \Psi_2^* = 0$. The appropriate homogeneous solution is

$$\Psi_{2H}^* = \left\{ \alpha_1 + \frac{\alpha_2}{S^{*2}} \right\} \sin^2 \theta \cos \theta, \quad (31)$$

where α_1, α_2 are constants. The complete second-order displacement function is therefore

$$\Psi_2^* = \left[\frac{2C_2}{\mu} \left\{ \frac{6}{S^{*3}} - \frac{18}{S^{*2}} + \frac{18}{S^{*5}} - 6 \right\} + \left\{ -\frac{3}{S^{*3}} + \frac{15}{S^{*2}} - \frac{9}{S^{*5}} - 3 \right\} \right] \sin^2 \theta \cos \theta. \quad (32)$$

The complete second-order displacement and stress components determined from (16), (19) and (32) are

$$\begin{aligned}
u_2^* &= \left[\frac{36C_2}{\mu} \left\{ -\frac{1}{S^{*5}} + \frac{3}{S^{*4}} - \frac{3}{S^{*3}} + \frac{1}{S^{*2}} \right\} + \right. \\
&\quad \left. + \left\{ -\frac{9}{2} \frac{1}{S^{*7}} + \frac{36}{S^{*5}} - \frac{45}{S^{*4}} + \frac{9}{2} \frac{1}{S^{*3}} + \frac{9}{S^{*2}} \right\} \right] \cos^2 \theta + \\
&\quad + \frac{12C_2}{\mu} \left\{ \frac{1}{S^{*5}} - \frac{3}{S^{*4}} + \frac{3}{S^{*3}} - \frac{1}{S^{*2}} \right\} + \\
&\quad + \left\{ -\frac{3}{2} \frac{1}{S^{*7}} - \frac{6}{S^{*5}} + \frac{15}{S^{*4}} - \frac{9}{2} \frac{1}{S^{*3}} - \frac{3}{S^{*2}} \right\}, \\
w^* &= \left[\frac{36C_2}{\mu} \left\{ -\frac{1}{S^{*5}} + \frac{2}{S^{*4}} - \frac{1}{S^{*3}} \right\} - \right. \\
&\quad \left. - \frac{3}{2} \frac{1}{S^{*7}} + \frac{18}{S^{*5}} - \frac{30}{S^{*4}} + \frac{27}{2} \frac{1}{S^{*3}} \right] \sin \theta \cos \theta,
\end{aligned} \tag{33}$$

and

$$\begin{aligned}
T_{SS}^{(2)*} &= \left[\frac{72C_2}{\mu} \left\{ -\frac{1}{S^{*8}} + \frac{7}{S^{*6}} - \frac{12}{S^{*5}} + \frac{9}{S^{*4}} - \frac{3}{S^{*3}} \right\} + \right. \\
&\quad \left. + \frac{84}{S^{*8}} - \frac{333}{S^{*6}} + \frac{360}{S^{*5}} - \frac{54}{S^{*3}} \right] \cos^2 \theta + \\
&\quad + \frac{12C_2}{\mu} \left\{ -\frac{10}{S^{*6}} + \frac{24}{S^{*5}} - \frac{21}{S^{*4}} + \frac{6}{S^{*3}} \right\} + \\
&\quad + \frac{9}{S^{*8}} + \frac{3}{S^{*6}} - \frac{120}{S^{*5}} + \frac{36}{S^{*4}} + \frac{18}{S^{*3}}, \\
T_{\phi\phi}^{(2)*} &= \left[\frac{72C_2}{\mu} \left\{ \frac{1}{S^{*8}} - \frac{6}{S^{*6}} + \frac{5}{S^{*5}} - \frac{1}{S^{*4}} \right\} + \right. \\
&\quad \left. + \left\{ -\frac{21}{S^{*8}} + \frac{135}{S^{*6}} - \frac{150}{S^{*5}} + \frac{45}{S^{*4}} \right\} \right] \cos^2 \theta + \\
&\quad + \frac{12C_2}{\mu} \left\{ \frac{6}{S^{*8}} + \frac{2}{S^{*6}} - \frac{6}{S^{*5}} + \frac{3}{S^{*4}} \right\} + \\
&\quad + \left\{ -\frac{12}{S^{*8}} - \frac{15}{S^{*6}} + \frac{30}{S^{*5}} - \frac{9}{S^{*4}} \right\}, \\
T_{\theta\theta}^{(2)*} &= \left[\frac{72C_2}{\mu} \left\{ \frac{2}{S^{*8}} - \frac{7}{S^{*6}} + \frac{7}{S^{*5}} - \frac{2}{S^{*4}} \right\} + \right. \\
&\quad \left. + \left\{ -\frac{45}{S^{*8}} + \frac{117}{S^{*6}} - \frac{210}{S^{*5}} + \frac{63}{S^{*4}} \right\} \right] \cos^2 \theta + \\
&\quad + \frac{12C_2}{\mu} \left\{ \frac{8}{S^{*6}} - \frac{14}{S^{*5}} + \frac{9}{S^{*4}} \right\} + \frac{12}{S^{*8}} + \frac{3}{S^{*6}} + \frac{90}{S^{*5}} - \frac{27}{S^{*4}}, \\
T_{S\theta}^{(2)*} &= \left[\frac{72C_2}{\mu} \left\{ -\frac{1}{S^{*8}} + \frac{5}{S^{*6}} - \frac{6}{S^{*5}} + \frac{5}{S^{*4}} - \frac{1}{S^{*3}} \right\} + \right. \\
&\quad \left. + \frac{48}{S^{*8}} - \frac{126}{S^{*6}} + \frac{240}{S^{*5}} - \frac{144}{S^{*4}} - \frac{18}{S^{*3}} \right] \sin \theta \cos \theta,
\end{aligned} \tag{34}$$

respectively.

Force-displacement relationship for the spherical inclusion

Consider a closed spherical surface $\partial\Sigma$ in the deformed body. The component of the resultant force in the X_3 direction, over $\partial\Sigma$ is given by

$$F_Z = \int_{\partial\Sigma} \left\{ T_{SS} \cos \theta - T_{S\theta} \sin \theta \right\} s_0 \sin \theta \, d\theta, \quad (35)$$

where s_0, θ are the coordinates of a particle on $\partial\Sigma$. Also on $\partial\Sigma$

$$s_0 = S + \epsilon u_1(s_0, \theta), \quad \theta = \theta + \epsilon \frac{w_1}{S}(s_0, \theta), \quad (36)$$

to order ϵ ; and to this order S may be replaced by s_0 . By considering the series expansions for T_{SS} and $T_{S\theta}$, (35) can be reduced to a form

$$F_Z = \epsilon F_Z^{(1)} + \epsilon^2 F_Z^{(2)}, \quad (37)$$

where

$$F_Z^{(1)} = \int_0^\pi \left\{ T_{SS}^{(1)} \cos \theta - T_{S\theta}^{(1)} \sin \theta \right\} s_0 \sin \theta \, d\theta, \quad (38)$$

and

$$\begin{aligned} F_Z^{(2)} = & \int_0^\pi \left\{ T_{SS}^{(2)} \cos \theta - T_{S\theta}^{(2)} \sin \theta - \frac{w_1}{S} \left[T_{SS}^{(1)} \sin \theta + T_{S\theta}^{(1)} \cos \theta \right] + \right. \\ & - u_1 \left[\frac{\partial T_{SS}^{(1)}}{\partial S} \cos \theta - \frac{\partial T_{S\theta}^{(1)}}{\partial S} \sin \theta \right] + \\ & \left. + \left[T_{SS}^{(1)} \cos \theta - T_{S\theta}^{(1)} \sin \theta \right] \left[\frac{1}{S} \frac{\partial w_1}{\partial \theta} + \frac{w_1}{S} \cot \theta \right] \right\} s_0 \sin \theta \, d\theta. \quad (39) \end{aligned}$$

Evaluating the integrals (38) and (39) we obtain

$$\epsilon F_Z^{(1)} = -6\pi\mu a \xi, \quad F_Z^{(2)} = 0. \quad (40)$$

The result $F_Z^{(2)} = 0$ confirms the fact that from the particular spatial symmetry of the problem the force F must be an odd function of the inclusion displacement ξ . Therefore the result $F = -6\pi\mu a \xi$ is valid to order ϵ^3 .

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