

NEW WHEEL ASSEMBLY DESIGN ON GRÉGOIRE-BESSON SP/SPML PLOUGH RANGE

BY NICOLAS DUBUC



NEW WHEEL ASSEMBLY DESIGN ON GRÉGOIRE-BESSON SP/SPML PLOUGH RANGE

PRESENTED BY

NICOLAS DUBUC

TO

DR. G.S.V. RAGHAVAN

BREE 490 - DESIGN 2

APRIL 1, 2008

McGill University
Faculty of Agricultural and Environmental Sciences
Department of Bioresource Engineering
Room MS1-027, MacDonald-Stewart Building, 21111 Lakeshore Rd.
Ste-Anne-de-Bellevue, Quebec H9X 3V9
Tel.: 514-398-7773 | Fax: 514-398-8387



EXECUTIVE SUMMARY

Farmers are facing tougher competition every day as agriculture continues to become a more globally integrated industry. In order to face this pressure they must reduce their production cost and increase their efficiency. Tillage is one of the target areas for cost reduction as it consumes a lot of energy and time. Although ploughing is slowly losing ground to other tillage practices, many speciality crops, climatic zones and niche markets continue to require the use of ploughing as a key practice in their tillage system. Grégoire-Besson is committed to fulfilling the needs of these customers and helping them improve their profitability. Increasing efficiency by design is the main goal of this project. By looking at the weak areas of the existing SP/SPML plough range, new concepts to improve the rear wheel design will be created. A design methodology will be established based on the most recent scientific and engineering data and techniques. Finally a work schedule and cost analysis will be proposed. The ultimate goal of the project is to design a virtual wheel assembly prototype for Grégoire-Besson's SP/SPML plough range.



TABLE OF CONTENTS

EXECUTIVE SUMMARY	4
TABLE OF CONTENTS	5
Introduction	6
THE INITIAL PROJECT SELECTION PROCESS	8
PORTRAIT OF THE COMPANY	9
HISTORY	
BUSINESS MODEL AND COMPETITORS	9
PROBLEM STATEMENT	10
PRODUCT BACKGROUND	10
PROBLEMS DEFINITION	1
MARKET CONSIDERATIONS	13
CURRENT PRODUCT OFFER	13
PRELIMINARY IDEAS	1!
PATENT REVIEW	15
PRELIMINARY RECOMMENDATIONS	
Scope	1
RESULTS	17
METHODOLOGY	18
STRUCTURAL MECHANICS	
MATERIAL SELECTION	
COMPONENTS SELECTION THEORY	2
HYDRAULIC CIRCUITS DESIGN THEORY	
Sources of Information	
Work Schedule	26
Work Flowchart	
ESTIMATED WORK TIME	26
Cost Analysis	28
Conclusion	31
ACKNOWLEDGMENTS	32
INDEX OF FIGURES AND TABLES	33
	34
ADDITIONAL DESIGN REFERENCES	35
APPENDIX A - GRÉGOIRE-BESSON SP/SPML SERIES PLOUGH BROCHURE	36



INTRODUCTION

Agriculture has experienced tremendous changes during the second part of the 20th century. Numerous technological and scientific developments during the post-war period have been widely adopted by farmers in developed countries to boost farm productivity and move agriculture from a subsistence activity to a globalized industry. Chemicals use has been one of the major changes, with a widespread utilization of pesticides to control crop pests and commercial fertilizers to balance crop nutrient inputs. Methods of doing field operations have changed, too. In North America, the last two decades saw the gradual replacement of conventional mouldboard ploughing with new conservation techniques such as no-tillage and minimum-tillage using chisel ploughs and discs. Europe is also experiencing a change of tillage practices, albeit at a slower pace than in North America. Many agronomists and machinery specialists have seen in this trend the potential extinction of ploughing as a tillage operation.

There are many factors making ploughing less attractive compared to conservation practices: high fuel cost, relatively slow work rate, high tractive force required, etc. Furthermore, ploughing is often blamed as one of the main cause of soil erosion resulting from the low amount of crop residue left at the surface. Although these concerns are totally justified, it is important to make some distinctions based on regional differences. Conservation practices are particularly well adapted to climates where large amounts of crop residue cover do not impede natural soil drying and warming; these dry and warm climates are mostly encountered in the American Midwest, the Canadian Prairies, Argentina, Brazil, South Africa and Australia. However many other important arable regions such as most of Europe and North Eastern North America experience high rainfalls and have relatively short growing seasons. In these cases, ploughing can be beneficial as part of a diversified tillage system.

The latter regions often receive large amounts of rain during harvest time, causing inappropriate soil conditions for harvest operations. Harvest often results in ruts and other soil damages which are best remedied by ploughing. In comparison to other primary tillage operations ploughing is the method that produces the best results



under wet conditions. Also, because it buries most crop residue, it leaves soil exposed for faster drying and warming. The burial of crop residue is also very important for some specialty crops (peas, beans) which must not be contaminated with soil. The fact that soil is completely moved to a depth of 150-250 mm also makes of the plough an excellent tillage instrument for roots and tuber crops (carrots, potatoes, etc.) which require a loose seedbed with not surface compaction.

In addition to the technical benefits of ploughing, the technique may soon make a come back in our fields as a method of reducing our dependency on chemicals, particularly pesticides. The European Parliament voted a new directive in 2007 calling for 50% reduction of active pesticide ingredients used in agriculture by 2017 (European Parliament, 2007). Ploughing is a method of choice to control crop pests and weeds. In particular, it is a very important and effective tool to control slug populations which are extremely damaging to wheat and oilseed rape crops.

Ploughing still has its place as a major tillage practice. However, to gain the most from the technique it is important to include it in an integrated sustainable farming system that includes tillage rotation, crop rotation and pesticides rotation.

As farmers have to compete in a global agricultural industry, it is important to have efficient equipments that will help reducing production costs and increase productivity. A major player in the tillage equipment industry in Europe and globally, Grégoire-Besson SA asked me to evaluate the current design of their SP/SPML reversible plough range and to produce a new wheel assembly design which has been demanded by customers in certain markets for a number of years.



THE INITIAL PROJECT SELECTION PROCESS

I had multiple project ideas prior to beginning this project. They all had one common point: agricultural engineering was to be the cornerstone of any project I would undertake. Having a good background in soil conservation and a great interest in machinery design, I decided to contact Mr. Cyril Thirouin, eng., who I met a few years ago when he worked in Quebec. Mr. Thirouin is now head engineer for Grégoire-Besson in France. He initially proposed me to work on the design of a new disc harrow frame to be built in Canada; he also put me in contact with Simon Bourque, manager of Grégoire-Besson Canada in St-Hyacinthe. The first meeting with Mr. Bourque consisted of defining what the project would look like and evaluate the amount of work required. After this initial meeting, I started evaluating the possible design options for the frame of the machine using the existing technical drawings. During a second meeting with Mr. Bourque at Macdonald Campus, we came to the conclusion that the disc harrow design was not suitable for the design course. We made a list of projects of interest for the company: strip-tillage row unit, subsoiler frame and spring-reset system and reversible plough wheel assembly. After a few weeks, Mr. Thirouin and Bourque agreed to offer me the possibility of designing a new wheel assembly for ploughs. This project will be detailed in the following pages.



PORTRAIT OF THE COMPANY

Grégoire-Besson SA is based in Montigné-sur-Moine, in Eastern France. It is a leader in tillage machinery in Europe and globally. Its product range includes mouldboard ploughs, disc ploughs, disc harrows, disc-tine cultivators, subsoilers, light cultivators and potato planters. In addition to its home base in France, the company also has international subsidiaries in the United Kingdom, Canada, Spain and Poland. It is a family-owned company, with Patrick Besson as the main shareholder and CEO of the company.

HISTORY

The origins of the company can be traced back to 1802 when Mr. Grégoire started a small shop in Montigné (Grégoire-Besson, 2007). During the following century it evolved into a small farm machinery manufacturing shop. In the 1960's and 1970's, the company grows quickly due to the success of its products. During the last two decades, the company continued to grow and took over other tillage equipment manufacturers (tines and discs) to widen its products offer. In the last few years Grégoire-Besson also established itself as the leader for large tillage equipment by establishing new world records for the area ploughed in 2005 and for the area disced in 2007.

BUSINESS MODEL AND COMPETITORS

Since Grégoire-Besson is a small company compared to giants like John Deere, CNH, Kuhn and Kverneland, it has established itself as a specialised company focusing on only one product type (tillage) for niche markets. It offers highly customisable machines that can be adapted to fit the specific needs of each customer. This highly adaptable product range also means that the company is able to fulfil the requirements of markets considered too small by large manufacturers. The main market for Grégoire-Besson is Europe. The main competitors of Grégoire-Besson are Kverneland (Norway), Kuhn (France) and Lemken (Germany). All product design is done in-house by the company's engineering department. Partnerships have been established with dozens of local firms for special services such as heat treatment and machining.



PROBLEM STATEMENT

PRODUCT BACKGROUND

As mentioned earlier, a reliable and innovative plough design is a key selling point for farmers who are always looking to increase their work efficiency while keeping operation and maintenance costs down. Grégoire-Besson's SP series ploughs were originally designed in the early 1980's (Thirouin, 2002). The original machine was designed to handle 4 to 6 furrows and the headstock was strong enough for tractors of 150 to 180 hp. During the years, farmers needs changed and the company responded by adding new equipments and options on the plough. For example, the range was expanded by adding 7 and 8 furrows models, new rock protection systems were offered and coulters were added as an option for regions like Eastern Canada.

All these modifications to the original design showed some of the flaws of this design and forced the engineers to return to the drawing board to create an improved version of what is now Grégoire-Besson's flagship semi-mounted plough range. However, Grégoire-Besson is still looking at improving some weak points of the machine.

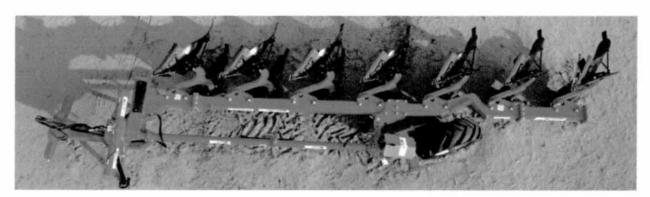


Figure 1: Top view of a Grégoire-Besson 7-furrow SPP9 plough (Thirouin, 2008).



PROBLEMS DEFINITION

Grégoire-Besson requested me to investigate a few issues that are all related to the positioning of the transport/depth control wheel. One of the main problems encountered by users is the difficulty of the rack-and-pinion turnover mechanism to flip the plough from one side to the other at the headland (fig. 2). This problem is due to the large weight of the plough and its attachments (coulters, skimmers, gauge wheels, etc.). In addition, machines operating in Eastern North America and to a certain extent in Europe also have to deal with the added weight of wet soil and residue sticking to the mouldboards (Thirouin, 2000). This phenomenon is further emphasised by the long distance between the centre of gravity of the plough and the axis of rotation. This is a direct result of the positioning of the wheel in the middle of the plough: in order to

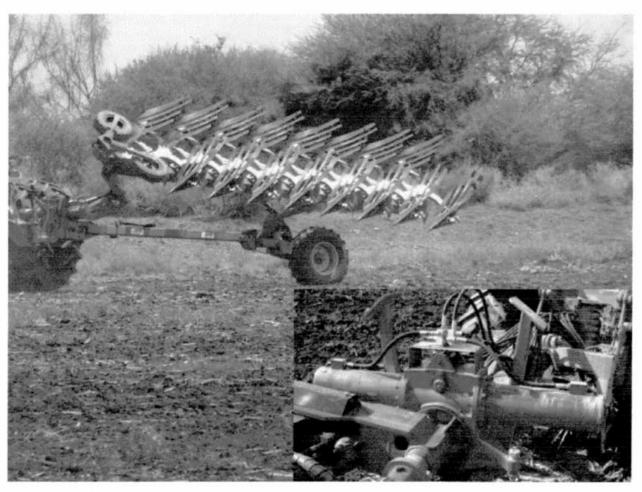


Figure 2: SPMLB9 plough during the turnover process (Thirouin, 2008). Inset: Rack-and-pinion turnover mechanism (Steenbeek, 2007).

accommodate the transport wheel between the plough Z-frame and the rotation axis (fig. 1) the latter must be moved farther from the Z-frame. This longer distance means that a greater torque is required at the turnover mechanism; in extreme conditions the design torque of the mechanism may be exceeded and the turnover process can only be done after removing some soil from the bodies.

Another impact of the positioning of the wheel is the behaviour of the plough in wet and hard soils. Many Canadian customers report that in very difficult conditions the tractor has very little control over the plough (Thirouin, 2000; Grégoire-Besson, 2004). This is mostly due to the positioning of the line of traction; a possible solution may be to put the wheel closer to the centre of gravity.

Another problem mentioned by many customers and outlined as the machine's weakest point by a renowned machinery magazine ("Vive la difference", 2008; Thirouin, 2002) is that the Z-frame can interfere with the wheel during the turnover process if the rear of the plough is not raised first. However, raising the backend to leave clearance for the Z-frame makes the plough unstable during turnover and increases the stress on the tractor linkage (Thirouin, 2002). Poor soil conditions on the headlands, such as ruts and holes, can also cause instability.

A design constraint also causes issues to customers who want to have a larger wheel to improve manoeuvrability: the current positioning of the wheel in the Z-frame limits tire diameter to less than 1100 mm. Many users would like to use 24R20.5 flotation tires (\varnothing 1260 mm); this requires a repositioning of the wheel.

Finally, another issue with the current design is that with its current positioning, the rear wheel acts as a pivot point on the plough frame. When the tractor hitch is raised due to uneven terrain or when exiting a furrow, the plough pivots about the wheel and the bodies behind the wheel go deeper. In very wet soil conditions as encountered in Eastern North America, having a single on-land wheel is problematic as it sinks in mud, thus increasing the working depth at the back. Both of these conditions lead to an



uneven work depth and quality. A current user (Mr. Gerard Steenbeek) and a potential buyer (Mr. Warren Schneckenburger) of SP series ploughs gave me their opinion on the current product and suggested some improvements. Mr. Schneckenburger (personal communication, January 2008) suggests that the plough should have two wheels at the back: one in the furrow and one on land. This would allow a better depth control in wet soil conditions as the furrow wheel will be on hard soil.

MARKET CONSIDERATIONS

Each market has different needs and the plough market follows the same rules. Most of the complaints and requests for improvements come from users and distributors in Canada and the Community of Independent States (CIS) (Thirouin, 2002). These markets are relatively small compared to the European market, but Grégoire-Besson wants to occupy this niche market. The technology developed to fit the needs of these two markets can also be transferred to European models if demand is sufficient. Current sales expectations for SP series ploughs are approximately 120 units per year globally, with 25 units exported in Canada. The limited size of the market means that we must ensure interoperability between the existing products and the new design to have as many common parts as possible between the two models.

CURRENT PRODUCT OFFER

The current product offer from Grégoire-Besson and its competitors in the semi-mounted market consists of two main types of ploughs: centre-carriage ploughs (fig. 3) and single rear wheel ploughs (fig. 4). The latter has the largest sales volume. Centre-carriage ploughs are usually larger than single wheel ploughs. Since they do not have a direction system on the central carriage, they are not very manoeuvrable and their use is limited to larger fields. Single wheel ploughs are more manoeuvrable due to the wheel direction system and the smaller distance between the wheel and the tractor.

Single wheel ploughs, which are the main object of my project, are available in 2 configurations: mid-mounted wheel and rear-mounted wheel (fig. 5 and 6). Each one has its advantages and disadvantages, which are presented in Table 1.



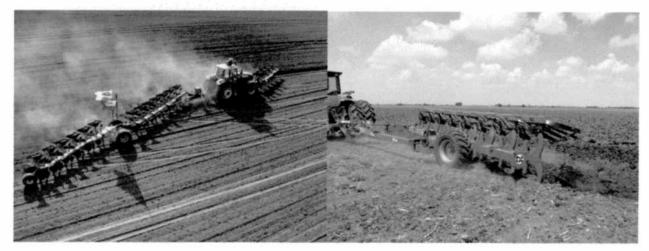


Figure 3: Centre-carriage plough (G-B, 2007). Figure 4: Single wheel plough (Thirouin, 2008).

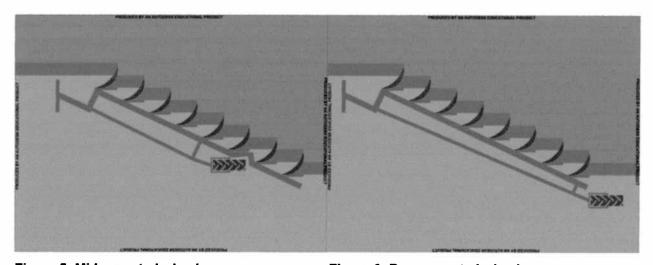


Figure 5: Mid-mounted wheel.

Figure 6: Rear-mounted wheel.

WHEEL TYPE	ADVANTAGES	DISADVANTAGES
M id-mount	- Wheel is within the working width - Highly manoeuvrable	 Complex Z-frame Poor weight transfer Uneven working depth More turnover torque required Unstable manoeuvres at headland
Rear-mount	Good weight transferGood depth controlLarger tires can be installedLower turnover torque	- Requires reinforced stabilisation bar - Less manoeuvrable unless good direction system is fitted - Wheel is not within working width

Table 1: Comparative chart for mid-mount and rear-mount plough wheels (Thirouin, 2002).



PRELIMINARY IDEAS

After having defined the problems affecting the machine, the following step of the design process is to gather as much information as possible about the design topic and to make a list of preliminary ideas that may be applicable to solve the problem. I also followed the design process proposed by Krutz et al. (1984) in *Design of Agricultural Machinery*. One of the main recommendations of this design process is to gather information about current models and competitive models. I reviewed what is offered by Grégoire-Besson and its competitors and I started making a list of features and concepts which may be of interest. In addition, I decided to do a patent review to see what are the main innovative concepts used by plough manufacturers as wheel as see if some of my preliminary ideas are already patented and require a licence to use them.

PATENT REVIEW

I focused my search on European patents organisations because the vast majority of plough manufacturers are located on the Old Continent. I found numerous interesting ideas which may help me solve the problems enumerated earlier. Among the best discoveries, I found a design filed by Charrues Bonnel in 1990 which uses two wheels at the back of a reversible plough (commercialised as a "quart-de-tour" plough) (Bonnel, 1990). This concept is very similar to the centre carriage used on large reversible ploughs, but integrates a direction system on the wheels. A similar concept was developed in 1992 by Michel Bugnot (Bugnot, 1992), but the primary goal is to install tillage and seeding implements to have a one-pass tillage and seeding train. Finally I also found a patent issued to Kuhn SA in 2003 (Paugam, 2003) which describes a turnover system. I am mostly interested in how the rear wheel attaches to the stabilisation bar and this patent may give me some ideas for a possible design.

PRELIMINARY RECOMMENDATIONS

Based on my product review and patent review, I decided to evaluate two designs of wheel assembly for the SP/SPML series ploughs. Since both designs have their advantages and disadvantages, I believe that it is important to model and compare both designs to see which one fits best to respond to Grégoire-Besson's requirements.



Both designs will have the same basic principle: they will have two wheels installed at the back, with one of them in the furrow and the other one on land. It seems to be the best option to control working depth accurately, increase stability and improve manoeuvrability. All these claims will have to be assessed once a preliminary design is made for each concept. One disadvantage of using two wheels at the back is that it increases the operating width of the machine considerably and limits on how close to a field edge the plough can work. One the primary goal of the design will be to minimize the working width of the wheel assembly. All these claims will have to be assessed once a preliminary design is made for each concept. The first design will consist of two wheels connected by a rigid axle (fig. 7). Such a concept has already been used on some Overum ploughs (fig. 8). The second concept will consist of two independent wheels connected to the frame via a specially designed frame (fig. 9).

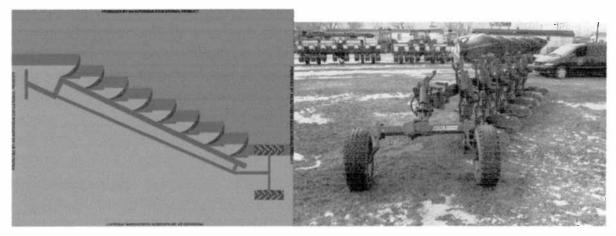


Figure 7: Rigid axle wheel assembly.

Figure 8: Rigid axle (Overum) (Thirouin, 2008).

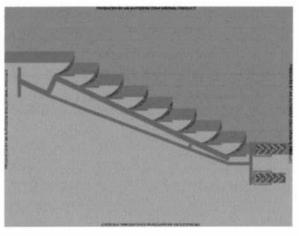


Figure 9: Independent wheels.



SCOPE

My goal for the next following months will be to design all the components required to build my two concepts of wheel assemblies. This will involve calculation of all the forces applied on the assembly (weight of the machine, rolling resistance, etc.). Once the forces acting on main components will be calculated, I will have to go through a material selection process to find the best suited materials to meet technical and cost constraints. The following step will be to select the various components (bushings, bearings, hydraulic cylinders, fasteners and welds, etc.) according to loads and fatigue cycles. I will also have to design the hydraulic system controlling the assembly. Finally I will spend a major part of my time modelling components in Pro/Engineer Wildfire 3 (Pro/E) and assembling the components. Once a complete assembly has been designed I will be able to model how it reacts to external forces and I will be able to adjust the parameters of the direction system.

I will work closely with Mr. Thirouin and Bourque and I will seek their input at all the important stages of the design to make sure that my designs meet all the requirements and needs of Grégoire-Besson and its customers.

RESULTS

The two virtual prototypes created with Pro/E will be evaluated on six main criteria: manufacturing cost, quality of depth control, machine stability, manoeuvrability, reduction of turnover torque required and physical dimensions. A qualitative analysis will be used to determine the importance and weight of each criterion. Of course, cost is likely to be the determining factor in the decision to proceed further in the development of this product (prototypes and field testing), but outstanding results in some of the criteria may offset the importance of cost as the determining factor.

The following section deals with the methodology I intend to use for the development and analysis of my design. These methods will be refined and adapted to the specific context of each component.



METHODOLOGY FOR PROBLEM SOLVING

Due to the wide scope of this project, I chose to divide the theoretical part of my design in 4 different aspects: structural mechanics, material selection, mechanical components and hydraulic circuits. Of course these design categories are highly interdependent and cannot be considered individually; the distinction between the 4 theoretical sections is only a tool to simplify the analysis of the methods required. Once all the required theoretical information will be on hand, all concepts will be merged together. The following section will provide an overview of the theory required to analyse all aspects of this design process.

STRUCTURAL MECHANICS

The first step of the design approach is to evaluate and analyse all the forces applied on the wheel assembly of the plough. Using basic mechanics techniques such as free-body diagrams it is possible to quickly summarize evaluate which equations must be used (Krutz, Thompson & Claar, 1984). External loads such as the weight of the plough are quite easy to calculate using manufacturing data (components weight, location of the centre of gravity, etc.). Soil rolling resistance R_r requires much more work and assumptions and can be derived using the approach developed by McKyes and Bekker (McKyes, 1985)

$$R_r = \left\lceil \frac{z + \delta_t}{d} \right\rceil N$$

with sinkage z, tire deflection δ_t , tire diameter d and load N; also

$$R_r = \frac{\left(\frac{2N}{d}\right)^{\frac{n+1}{n}}}{\left(bk\right)^{\frac{1}{n}}} + \frac{\delta_t N}{d} = \frac{bp^{\frac{n+1}{n}}}{2k^{\frac{1}{n}}} + \frac{\delta_t N}{d}$$

with tire rpm n, tire width b, contact pressure p and terrain deformation exponent n. These equations will require assumptions about the soil types and properties. In addition tire characteristics (unloaded and loaded diameters, contact area, recommended operating pressure) must be obtained from tire manufacturers to



calculate accurate estimates of rolling resistance. It is important to note that we are looking for maximum values of rolling resistance.

The state of a stress is required to select materials as well as for the proper sizing of structural components. Stresses are divided in two main categories: simple loading axial stresses and combined biaxial stresses. While axial stresses are easily calculated with simple engineering formulas, Mohr's Circle represents a powerful tool to analyse more complex cases such as combined stresses and three-dimensional stresses (Juvinall & Marshek, 2006). If the stresses on a component are known, it is possible to determine the principal stresses, the principal directions and the maximum shear stresses. Mohr's Circle equations for combined stresses are (Juvinall et al., 2006)

$$\sigma_{1}, \sigma_{2} = \frac{\sigma_{x} + \sigma_{y}}{2} \pm \sqrt{\tau_{xy}^{2} + \left(\frac{\sigma_{x} - \sigma_{y}}{2}\right)^{2}}$$

$$2\phi = \tan^{-1}\frac{2\tau_{xy}}{\sigma_{x} - \sigma_{y}}$$

$$\tau_{\text{max}} = \pm \sqrt{\tau_{xy}^{2} + \left(\frac{\sigma_{x} - \sigma_{y}}{2}\right)^{2}}$$

$$\sigma_{\phi} = \frac{\sigma_{1} + \sigma_{2}}{2} + \frac{\sigma_{1} - \sigma_{2}}{2}\cos 2\phi$$

$$\tau_{\phi} = \frac{\sigma_{1} - \sigma_{2}}{2}\sin 2\phi$$

Since these equations only produce average stress values, it is necessary to calculate exact values at stress concentration points. Stress concentration regions are usually located around geometry changes (holes, fillets, notches). These regions exhibit much higher stresses so it is necessary to evaluate the maximum stresses in the regions to select materials and size components appropriately. There are two methods available for this: finite elements analysis (FEA), which requires sophisticated computer software, and stress concentration factors (Juvinall et al., 2006). The latter will be used

at the initial stages of design to approximate closely stress values, but I will try to make use of FEA on complete components to make sure that the stress concentration factors are appropriate. The theoretical stress concentration equation is (Krutz et al., 1984)

$$\sigma_{\max} = K_f \sigma_{nom}$$
.

Values of stress concentration factor K_f for numerous geometries can be found in most advanced mechanics and component design textbooks.

Finally it will be necessary to calculate the turnover torque of the new designs to make sure that it meets the capacity of the current rack-and-pinion mechanism. The required torque is calculated by multiplying the weight of the plough by the distance of the centre of gravity from the rotation axis. The torque supplied by the mechanism is equal to the hydraulic force (area times pressure) multiplied by the radius of the pinion wheel.

MATERIAL SELECTION

Selection of adequate materials is a very important step in the design process. Many factors must be analysed to come up with the best material for the operating conditions. Although I am likely to use the same materials already used on the existing machines, it is important to go through the selection process to make sure that the materials selected fit the application performance requirements. Material selection is based on using accurate material properties, which are available from ASTM, material suppliers and engineering textbooks. Ashby's material selection charts are also an excellent tool to start with. They are a graphical presentation of properties relationships for various materials. *Fundamentals of Machine Component Design*, by Juvinall and Marshek (2006) also explains very well the steps and criteria for material selection.

Some of the key performance characteristics involved in my design include strength, rigidity, durability, reliability, cost, weight, productibility and availability. The cost aspect is especially important: it must include the cost of the raw material as well as labour cost of machining it and overhead, to come up with a total cost of fabricated part. This means that selecting the cheapest material does not always result in a

cheaper fabricated part. The aim of the selection process is to achieve the best overall performance per unit cost. This is defined as the Selection Index (Juvinall et al., 2006)

Selection index =
$$\frac{(availability) \times (performance)}{(cost)}.$$

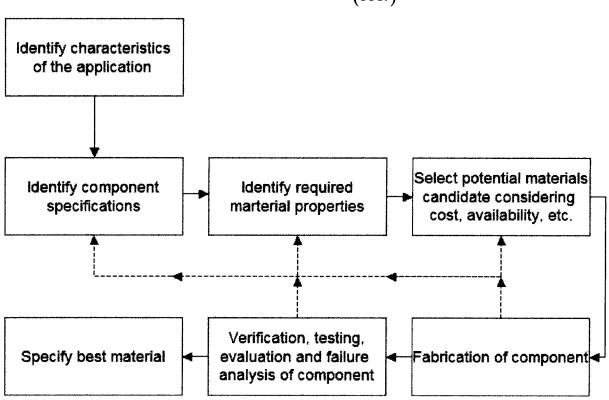


Figure 10: Material selection process for a machine component (Juvinall et al., 2006).

COMPONENTS SELECTION THEORY

Selection of appropriate mechanical components will have a direct impact on the reliability of the wheel assembly. Since most of these components will not be designed and manufactured in-house, but rather purchased from external suppliers, it is important to evaluate appropriately which components fit best the proposed performance characteristics. This section deals specifically with threaded fasteners, bushings and bearings. Welding theory is also included in this section. A primary concern of components selection is to select components already in use on other machines manufactured by the company whenever it is possible. Having as many common parts as possible between models will ensure lower part cost and reduce the part stocks that have to be supported by the company and distributors.

The two types of fastening which will be used in this design are bolts and welds. Each one has its advantages and disadvantages: bolts can be installed and removed easily and non-destructively (Juvinall et al., 2006) whereas welds are permanent. However, one of the main disadvantages of threaded fasteners is their tendency to loosen and disassemble. This loosening issue has already been noticed on SP series ploughs (Thirouin, 2000). The problem has been sourced to inadequate bolts and lock nuts grading: the threads are too soft and give way when subjected to large forces. Surface treatments increase friction and provide resistance to loosening.

Because the wheel assembly is a highly critical component of the machine, threaded fasteners selection cannot be conducted arbitrarily. It is recommended to use a safety factor of 3 to 4 when using known materials subjected to uncertain stress conditions (Juvinall et al., 2006). The starting point for bolt selection is to use engineering judgement to select the appropriate steel grade and the associate stress concentration factor. Based on the nominal bolt load and the chosen safety factor, design overload is calculated and using (Juvinall et al., 2006)

$$\sigma = \frac{F_i}{A_t} K_f,$$

we find the thread area A_t of the bolt. Using standard bolt size tables, the proper size can be selected. Welding has the advantage of being less costly than threaded fasteners for joining machine members (Juvinall et al., 2006). However due to the permanent nature of welding it can only be used on main structural members. Proper selection of welding rod is important to make sure that the tensile strength of the weld is appropriate for the loading of the structural members.

Journal bearings have many advantages: they have very little service requirements, have a low cost and have simple enclosure requirements (Krutz et al., 1984). These plain bearings cannot be used anywhere however. Their use is limited to shafts with slow rotation speeds or not constantly rotating. This makes journal bearings well suited to pivots and articulations on the plough frame. The selection process for journal bearings is quite complex and requires numerous assumptions. Lubrication

conditions must be determined to ensure minimal frictional drag force. Diameter is determined by shaft size and length is chosen in accordance with application unit load *P*, where (Juvinall et al., 2006)

$$L = \frac{F}{P}.$$

Length to diameter ratio is necessary to calculate the bearing characteristic number S, defined as (Juvinall et al., 2006)

$$S = \left(\frac{R}{c}\right)^2 \frac{\mu n}{P}$$

(with pressure P and dynamic lubricant viscosity μ) which can be used to determine bearing clearance. Additional calculations can find the required lubrication rate and interval.

Rolling elements bearings are more expensive than journal bearings, but they are better suited to faster rotation speeds and high starting loads. The main area of use is the rear wheel. Adequate bearing type is based on the type of loading: radial, thrust or combination (Krutz et al., 1984). To select the appropriate bearing, we must look at the grade of precision, lubrication, enclosure and basic load (Juvinall et al., 2006). A design life and reliability factor must also be specified. In the case of this plough, the design life is estimated at 5000 hours and 90% reliability is required. Application factors K_a must be selected based on the type of application and bearing. Bearing rated capacity C_{reg} is calculated with (Juvinall et al., 2006)

$$C_{req} = F_e K_a \left(\frac{L}{K_r L_r} \right)^{0.3}$$

with equivalent force F_e , design life L for a radial load, life adjustment reliability factor K_r and rated capacity design life L_r . Then using standard bearing sizing charts, we find the appropriate bearing for the type and size of loading.

HYDRAULIC CIRCUITS DESIGN THEORY

The hydraulic circuits controlling the wheel assembly are a crucial part of the design. Hydraulic components will be used to control the lifting and lowering of the plough and to control the direction system. The latter part is particularly important as the quality of the direction system will determine how manoeuvrable the plough is (this is a key point for design success).

The process of designing a hydraulic circuits starts with an analysis of job requirements (Burton & Bitner, 2008). In this particular case we must analyse the load to determine what is the required velocity profile, the burden and burden profile and the hydraulic force profile. These physical system characteristics help to determine the size of actuator required to perform the job. In addition actuators must be sized to be compatible with current tractors oil flow and operating pressure. Next is to establish flow and pressure profiles to ensure that the system will work within tractor operating constraints at all times. In order to determine complete system efficiency, operating horsepower must be calculated.

After all these system characteristics are known, it is possible to draw a hydraulic circuit. At every important part of the circuit, pressure, flow, and horsepower profiles must be plotted to ensure that the circuit is sufficiently efficient. If efficiency is too low, the circuit must be redesigned to reach acceptable efficiency. Because of the importance of the hydraulic system in this design, both from safety and machine performance points of view, we cannot redesign by compromising on design constraints (Burton et al., 2008). Once the circuit has acceptable performance characteristics, the final step is to select system components (actuators, valves, hoses, accumulators, etc.) based on performance and cost.

Sources of Information

The technical and theoretical information for this project comes from a wide variety of sources. I obtained some information about problems and suggested improvements from current and potential machine users. Company internal reports are also a tremendous source of information: all warranty claims are analysed and the company keeps extensive records. Grégoire-Besson also supplied me with excellent reports dealing with operating conditions in potential markets. Finally much of the theoretical aspect of this design comes from engineering standards (ASTM, ASABE), engineering textbooks and course notes. A list of additional design references can be found after the reference section (page 35).



WORK SCHEDULE

WORK FLOWCHART

The following flowchart depicts an overview of the complete design process from the project selection and brainstorming process up to the final design delivery to Grégoire-Besson.

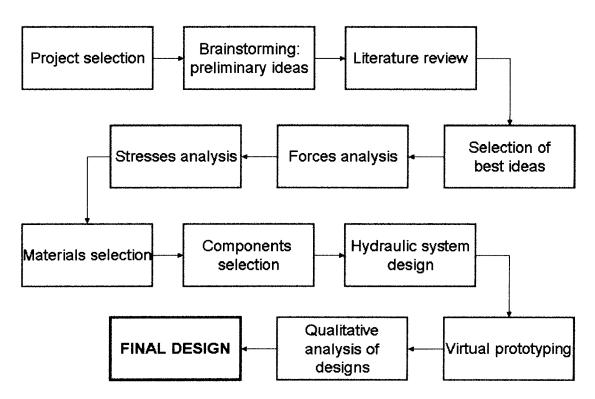


Figure 11: Complete design process flowchart.

ESTIMATED WORK TIMES

Table 2 shows the estimated time required to complete each step of the design. The schedule indicates tentative dates of completion of each step of the design and is subject to change based on unforeseen time and design constraints. It is based on course requirements and additional requirements by Grégoire-Besson. Part of the design work will be conducted during summer time as part of an internship at Grégoire-Besson Canada in St-Hyacinthe.



Month	TASK	TIME (H)
May 2008	 Analysis of current design (Pro/E) 	5
	 Evaluation of forces on wheel assembly 	10
	Modelling of turnover forces based on plough	12
	configuration (create Excel program)	
June 2008	Qualitative analysis of SP series plough and	10
	competitive designs	
	Marketing analysis	10
July 2008	 Stress analysis in structural components of the 2 	8
	concepts	
	Finite elements analysis of stresses	10
	Material selection	5
August 2008	Hydraulic system design	10
	Hydraulic components selection	3
	Mechanical components design and selection	15
September 2008	Technical drawings and virtual prototyping	40
	(Pro/E)	
October 2008	Optimisation of direction system	10
	 Qualitative analysis of design options 	5
November 2008	Final design report development	20
	Final presentation development	6
December 2008	Report submission and presentation	1
	TOTAL	180

Table 2: Proposed work schedule and time requirements.



COST ANALYSIS

At this stage of the project, it is not possible to evaluate the total cost of the wheel assembly (materials, work, design, etc.). However it is necessary to conduct a financial analysis of the cost of the design process itself to make sure that this cost meets the company's financial objectives in research and development. An accurate analysis of this cost is necessary as this investment in R&D will be reflected on the final cost of the product.

The data used to calculate the various hourly rates are based on industry standards for medium engineering firms in Canada. However it should be noted that these references are for consulting firms doing work for external customers. I assumed that they are equivalent the rates used in manufacturing firms. Rates and fees are given in Table 3. Rates for engineers and technicians include administrative fees (secretaries, accounting, legal fees, office supplies, etc.).

ÎTEM	Hourly rate (CA\$)
Engineer	75.00
CAD technician	32.00
Computer modelling (Pro/E)	10.00
Computer modelling (FEA)	10.00
Travelling	0.50 per kilometre
External consulting	75.00

Table 3: Rates and fees for design.

The cost of each step of the design is based on the work schedule presented in Table 2. In addition 25 hours of work are assumed for this first part of the design process and 5 hours of work is added for external consultants. Table 4 details the budget of the design process.



TASK	İTEM	TIME (H)	TOTAL COST
			(CA\$)
Preliminary design process	Engineer	25	1875.00
Analysis of current design (Pro/E)	Engineer	5	375.00
Evaluation of forces on wheel assembly	Engineer	10	750.00
Modelling of turnover forces based on	Engineer	12	900.00
plough configuration			
Qualitative analysis of SP series plough and	Engineer	10	750.00
competitive designs			<u> </u>
Marketing analysis	Engineer	10	750.00
Stress analysis in structural components of	Engineer	8	600.00
the 2 concepts			
Finite elements analysis of stresses	Engineer	10	750.00
	FEA software	***************************************	100.00
Material selection	Engineer	5	375.00
Hydraulic system design	Engineer	10	750.00
Hydraulic components design	Engineer	3	225.00
Mechanical components design and	Engineer	15	1125.00
selection			
Technical drawings and virtual prototyping	CAD technician	40	1280.00
(Pro/E)	Pro/E software		400.00
Optimisation of direction system	Engineer	10	750.00
Qualitative analysis of design options	Engineer	5	375.00
Final design report development	Engineer	20	1500.00
External consulting	Consultant	5	375.00
Travelling fees		500 km	250.00
	Тот	AL (CA\$)	14255.00

Table 4: Design process budget details.



It is quite easy to find the estimated cost per unit sold. Assuming that 25 units are sold every year, that the design is used during 5 years before being replaced by a newer design (amortization period of 5 years), and estimating the interest rate at 6%, the total research and development cost per unit sold is approximately CA\$135.00.



CONCLUSION

The research done for this design proposal showed that there is a growing potential market for an upgraded version of the SP/SPML plough range. Furthermore, the design concepts selected at the end of the brainstorming and analysis process will help solve numerous issues that have been observed the manufacturer and machine users and they will ultimately make the machine a more efficient tillage tool. The methodologies outlined in this proposal will the base point for the next steps of the design process which will be conducted during summer and fall 2008. The outcome of this extensive design process will be a complete virtual prototype with specifications for each component. A real-life working prototype would be ideal for field testing and further analysis of the design, but due to time constraints it is unlikely that a prototype be built before December 2008. However if the concepts meet all the requirements of Grégoire-Besson and after further market analysis, working prototypes will probably be built for field testing in 2009.



ACKNOWLEDGEMENTS

For their suggestions and support already given and promised for the future of this project, I would like to extend my appreciation to Mr. Cyril Thirouin of Grégoire-Besson and Mr. Simon Bourque of Grégoire-Besson Canada. Their cooperation was essential to the success of this project. Also I would like to thank Dr. G.S.V. Raghavan for his guidance and help.



INDEX OF FIGURES AND TABLES

FIGURE 1	TOP VIEW OF A GRÉGOIRE-BESSON 7-FURROW SPP9 PLOUGH	10
FIGURE 2	SPMLB9 PLOUGH DURING THE TURNOVER PROCESS. INSET: RACK-AND-PINION TURNOVER MECHANISM	11
FIGURE 3	CENTRE CARRIAGE PLOUGH	14
FIGURE 4	SINGLE WHEEL PLOUGH	14
FIGURE 5	MID-MOUNTED WHEEL	14
FIGURE 6	REAR-MOUNTED WHEEL	14
FIGURE 7	RIGID AXLE WHEEL ASSEMBLY	16
FIGURE 8	RIGID AXLE (OVERUM)	16
FIGURE 9	INDEPENDENT WHEELS	16
FIGURE 10	MATERIAL SELECTION PROCESS FOR A MACHINE COMPONENT	21
FIGURE 11	COMPLETE DESIGN PROCESS FLOWCHART	26
Table 1	COMPARATIVE CHART FOR MID-MOUNT AND REAR-MOUNT PLOUGH WHEELS	14
TABLE 2	PROPOSED WORK SCHEDULE AND TIME REQUIREMENTS	27
TABLE 3	RATES AND FEES FOR DESIGN	28
TABLE 4	DESIGN PROCESS BUDGET DETAILS	29



REFERENCES

Bonnel, D. Charrue réversible semi-portée sur deux roues. Institut National de la Propriété Industrielle Patent 90 02365, 1990.

Bugnot, M. Charrue semi-portée à essieu arrière. Institut National de la Propriété Industrielle Patent 92 13618, 1992.

Burton, R.T., & Bitner, D.V. (March 2008). Lecture notes: ME490.3 – Hydraulic Circuit Design and Fluid Power Systems.

Cahier des charges: charrue réversible semi-portée monoroue. (2004, December). Internal report. Grégoire-Besson SA.

European Parliament Web site. (2007). Retrieved March 12, 2008, from http://www.europarl.europa.eu/news/public/story_page/064-11884-295-10-43-911-20071019STO11857-2007-22-10-2007/default_en.htm

Grégoire-Besson Web site. (2007). Retrieved January 6, 2008, from http://www.gregoire-besson.fr/accueil.php?id rub=0&lg=en.

Juvinall, R.C., & Marshek, K.M. (2006). Fundamentals of Machine Components Design (4th ed.). Hoboken, NJ: John Wiley & Sons, Inc.

Krutz, G., Thompson, L., & Claar, P. (1984). *Design of Agricultural Machinery.* Hoboken, NJ: John Wiley & Sons, Inc.

McKyes, E. (1985). Soil Cutting and Tillage. Amsterdam, NL: Elsevier.

Paugam, D., Gabard, J.-N., & Perrinel, C. Charrue réversible semi-portée. Institut National de la Propriété Industrielle Patent 03 02196, 2003.

Steenbeek, G. (2007). ON, Canada.

Thirouin, C. (2008, February). *Projet 6-9 corps – roue arrière.* [CD-ROM]. Grégoire-Besson SA.

Thirouin, C. (2002, January). Projet SPWK 11 II. Internal report, Grégoire-Besson SA.

Thirouin, C. (2000, April). Rapport technique SP W P 9 Canada. Internal report, Grégoire-Besson SA.

Vive la différence – Practical test: Grégoire-Besson SPMLW9 semi-mounted plough. (2008, January). *profi International Tractors and Machinery*, 16-19.



ADDITIONAL DESIGN REFERENCES

2 gammes: SPF9 et SPL9. (2002). Montigné-sur-Moine, France: Grégoire-Besson SA.

ASM Engineered Materials Reference Book (2nd ed.). (1994). Materials Park, OH: American Society for Metals International.

Buckingham, F., & Pauli, A.W. (1993). Fundamentals of Machine Operations: Tillage. Moline, IL: John Deere Publishing.

Charrues semi-portées EuroDiamant et VariDiamant. (2003). Alpen, Germany: Lemken GmbH & Co.

Finnemore, E.J., & Franzini, J.B. (2002). *Fluid Mechanics with Engineering Applications* (10th ed.). New York: McGraw Hill.

Gammes SPER 7 – SPER W7. (2002). Montigné-sur-Moine, France: Grégoire-Besson SA.

Mangonon, P.L. (1999). *The Principles of Material Selection For Engineering Design*. Upper Saddle River, NJ: Prentice Hall.

McKyes, E. (1989). Agricultural Engineering Soil Mechanics. Amsterdam, NL: Elsevier.

Putting hardware flesh on concept bones – Feeder design and development. (2008, January). *profi International Tractors and Machinery*, 34-37.

SP SPML Compact High Output Single Wheel Plough. (2007). Montigné-sur-Moine, France: Grégoire-Besson SA.

Srivastava, A.K., Goering, C.G., Rohrbach, R.P., & Buckmaster, D.R. (2006). *Engineering Principles of Agricultural Machines* (2nd ed.). St. Joseph, MI: American Society of Agricultural and Biological Engineers.

Toogood, R. (2006). *Pro/ENGINEER Wildfire 3.0 Advanced Tutorial*. Edmonton, Alberta: SDC Publications

Toogood, R. (2006). *Pro/ENGINEER Wildfire 3.0 Tutorial & Multimedia CD.* Edmonton, Alberta: SDC Publications.

Varilarge semi-portée à haut rendement. (2000). Kvernaland, Norway: Kverneland Klepp AS.

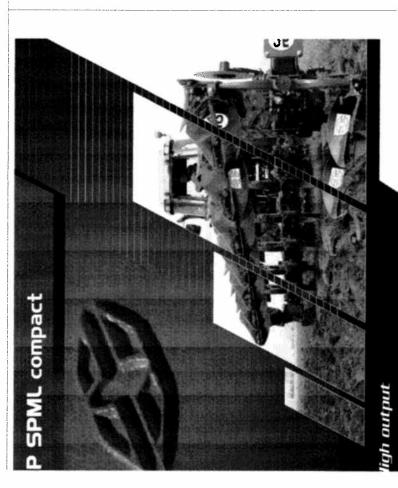


APPENDIX A

GRÉGOIRE-BESSON SP/SPML SERIES PLOUGH BROCHURE



36



SINGLE WHEEL PLOUGH



www.gregoire-besson.com

ORWARD WITH YOU

SP9-SPW9

150-300 Hp



Performance

Flexibility

Simplicity for a long life

For the long life of the frame (180x180x10),it is fabricated to the minimum, to keep the mechanical qualities of steel intact. After drilling the tube, bushes are welded in to Insure the ment of the frame. This way of manufacturing, with the bus of vedding parts togethen as much as possible, reduces the risk of loosening, to obtain the best life of your implement.



SP compact ploughs are equipped with a salf steering depth/fransport wheel. This allows easy manoeuvres on the headlands or in transport position.

The wheel support is linked to the turnover mechanism, in accordance to reduce the stress on the wheel. The wheel stays parallel to the furrow for less pulling requirements.



180 x 180 mm

1 × †

w

100 ou 114 cm 71 / 76 / 81 cm

件性

¥

Hough easy to modify

Due to the design of the frame, it will be possible to fit tyres with a wide diameter. The plough will pass over the obstacles without problem, and will increase the comfort

SP Compact range has been designed, to be able to offer a product which will flow the development of your farm. This plough has the possibility to be equipped with 2 additional turnow. Betant from Gragoire-Beason makes it possible to add an axtra furrow before the depth wheel, to allow the beat possible traction.

240-270

190-240 3100

160-190

140-160 2500

2800

æ W

3400

12-20" / 14-22"

386 models have some common design features which make Gregoire Besson ploughs well know:



e headstock is linked to the plough 1 a cast steel cardan, which allows a a ming angle of 110°.

is cardan can be equipped with a hyaulic compensation cylinder, which Il act directly on the top link. With this tented system, you can reduce the aft of the tractor up to 30%.

ong a better traction, this system used transport position allows a better nifort of the driver, working as a shock

All the single wheel semi mounted ploughs are available with some hitchs with various options. Fixe or automatic hitch, quick coupler cat II, III or IV, ...

To ensure a good resistance in the time, the body support is a welded cast part. The moulded support is hollow, which increases its solidity by absorption of the shocks. With its fleeling contour of the body, the residues

Inique design of the frame

Specific design of the frame allows easy turnover due to a better position of the wheel. As the wheel is totally integrated to the frame, the plough becomes more easy to puli.

ck and pinion mechanism, operated by two hyaulic cylinders ensures constant, precise and north easy operation during turnover operations. is system developped by Grégoire-Besson is now ilknow in the world for his high level of reliability

It is also possible to equip the plough with wider tyres (up to 1220 mm), for a better comfort and also a better control of the working depth in wet conditions (for example). This specification allows the SP and SPL ranges, to take out the wheel mark by the rear furrow.

uipped with some cylinders of 35 T, this system skes possible to turn the plough easely and with-tishock loads for the tractor and the plough.

ilknow in the world for his high d his low cost of maintenance.

A bower centre of gravity makes it possible to offer a plough mach more stable in transport or during headland operations. A plough more stable = more confrort and less mechankal stress for the plough and the tractor.

A great choice of safety devices to adapt to all the conditions

ment can move from top to bottom, and tran left to regit without the articula-tion being damagnd. The porten of safety use a double link. age and a cylinder fixed on the end of the element. Hydraulic safety device Gregoire-Ber is assembled on 4 ball joints. Each

> ments working in ground, without stone and in light, medium, and heavy solic without rocks. During the shearing of the bolt, the legs sweek and is cleared away from the obstacle. Depending on the conditions, there is a choice of bolt resistance (8.8 or 10.9).

This type of safety is suitable for imple-A safety bolt for the heavy

This system of safety uses a double link-age and a cylinder fred on the end of the element. In comparation of the Y system, E Apleaulic device is using ball ing on the articulation, to allow more fleeblity in heavy solls.



manually or hydraufically

\$59 / SPMLS : Adjustment of furrow width from 12s to 20s or from 14s to 22s, according to the interbody clearance 100 or 114 cm.

has press on the machanism. It is han possible to regulate the working didth in all position. The linkage can ke be easily reached for maintenance and adding or removing of eater fur-war. The pivot poems are bushed and reseable which ensures great reliabili-SPWB / SPMLW9: The working width adjustment system uses a double exter-











SPML9-SPMLW9 In Furnaw/On land semi mounted plough

0

ISO-290 Hp

Adaptibility Ergonomic Reliability

Possibility to work land and in-furrow

Depending on the soil and though on the type of tractors, it is important to keep the possibility to change your plough from the on-land to in furrow position, and reverse. The SPML Compact range is offering this possibility, and in a few minutes the plough can be few minutes the plough can be changed. Again, this specification makes your Gragaine-Besson thin makes your Gragaine-Besson thin mister your Gragaine-Besson thin mister your Gragaine-Besson thin mister your Gragaine-Besson thin mister your Gragaine-Besson.



Reliability is priority

180 x 180 mm

Į **×**

To ensure perfect reliability, the SPML 9 range, has been designed with a specific stabilisation frame. The turnover system (rear and pinon) allows a comfortable and precise movement of the plough, which will contribute to a better long life of your investment.

œ

9

so

71 / 76 / 81 cm

100 ou 114

12-20" / 14-22"

B,Y,Z

Z

IT: FT9



240-290 5100

200-240 4800

170-200

150-170 4200

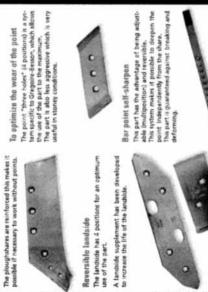
42 1

4500

Reinforced share guarantees output Gregoire-Besson: Original wearing parts of

ignal wearing parts of Gregolfe-sson are of higher quality with rimal freatments 180 kg. As well Their design, these spare parts re considered for an optimum use, ering to you low cost wearing part.

in all fields.



Bar point self-sharpon

This part has the advantage of being adjusti-able findipopitor) and reventible. This system makes it possible to deepen the point independently from the share. This part is guaranteed against threating and deforming.

Mais skimmer To choose a skimmer according to the volu Mixed skimmer Universal skimmer

Mouldboards are mainly characterised by their length and shape. To adapt to all the continons of use, Gregoire Besson offers a broad choice of mouldboards, short", "Inoly," full, slatted, helicoldal, cylin-dirial or mixed form ("American mouldboards").

A broad range of mouldboards

to suit all the conditio

Helicoidal mouldboard

Cylindrical mouldboard



Plastic mouldboard

Slatted mouldboard

www.gregoire-besson.com



49230 Montfaucon / Montigné Sur Moine - France

Authorized dealer

